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atmospheric and space flight control systems including aircraft, rockets (missiles and launch vehicles), entry vehicles and spacecraft (both orbital and attitude control).

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introduces the reader to the concepts of modern control theory applied to the design and analysis of general flight control systems in a concise and mathematically rigorous style it presents a comprehensive treatment of both atmospheric and space flight control systems including

Advanced Control of Aircraft, Spacecraft and Rockets introduces the reader to the concepts of modern control theory applied to the design and analysis of general flight control systems in a concise and mathematically rigorous style. It presents a comprehensive treatment of both atmospheric and space flight control systems including

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aircraft, rockets (missiles and launch vehicles), entry vehicles and spacecraft (both orbital and attitude control). The broad coverage of topics emphasizes the synergies among the various flight control systems and attempts to show their evolution from the same set of physical principles as well as their design and analysis by similar mathematical tools. In addition, this book presents state-of-art control system design methods - including multivariable, optimal, robust, digital and nonlinear strategies - as applied to modern flight control systems. Advanced Control of Aircraft, Spacecraft and Rockets features worked examples and problems at the end of each chapter as well as a number of MATLAB / Simulink examples housed on an accompanying website at <http://home.iitk.ac.in/~ashtew> that are realistic and

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representative of the state-of-the-art in flight control.

Automatic Control of Atmospheric and Space Flight Vehicles is perhaps the first book on the market to present a unified and straightforward study of the design and analysis of automatic control systems for both atmospheric and space flight vehicles. Covering basic control theory and design concepts, it is meant as a textbook for senior undergraduate and graduate students in modern courses on flight control systems. In addition to the basics of flight control, this book covers a number of upper-level topics and will therefore be of interest not only to advanced students, but also to researchers and practitioners in aeronautical engineering, applied mathematics, and systems/control theory.

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This book offers a unified presentation that does not discriminate between atmospheric and space flight. It demonstrates that the two disciplines have evolved from the same set of physical principles and introduces a broad range of critical concepts in an accessible, yet mathematically rigorous presentation. The book presents many MATLAB and Simulink-based numerical examples and real-world simulations. Replete with illustrations, end-of-chapter exercises, and selected solutions, the work is primarily useful as a textbook for advanced undergraduate and beginning graduate-level students.

This is the first book on adaptive aeroservoelasticity and it

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presents the nonlinear and recursive techniques for adaptively controlling the uncertain aeroelastic dynamics Covers both linear and nonlinear control methods in a comprehensive manner Mathematical presentation of adaptive control concepts is rigorous Several novel applications of adaptive control presented here are not to be found in other literature on the topic Many realistic design examples are covered, ranging from adaptive flutter suppression of wings to the adaptive control of transonic limit-cycle oscillations

Flight Vehicle Dynamics and Control Rama K. Yedavalli, The Ohio State University, USA A comprehensive textbook which presents flight vehicle dynamics and control in a unified

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framework Flight Vehicle Dynamics and Control presents the dynamics and control of various flight vehicles, including aircraft, spacecraft, helicopter, missiles, etc, in a unified framework. It covers the fundamental topics in the dynamics and control of these flight vehicles, highlighting shared points as well as differences in dynamics and control issues, making use of the 'systems level' viewpoint. The book begins with the derivation of the equations of motion for a general rigid body and then delineates the differences between the dynamics of various flight vehicles in a fundamental way. It then focuses on the dynamic equations with application to these various flight vehicles, concentrating more on aircraft and spacecraft cases. Then the control systems analysis and design is carried out both from transfer function, classical

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control, as well as modern, state space control points of view. Illustrative examples of application to atmospheric and space vehicles are presented, emphasizing the 'systems level' viewpoint of control design. Key features: Provides a comprehensive treatment of dynamics and control of various flight vehicles in a single volume. Contains worked out examples (including MATLAB examples) and end of chapter homework problems. Suitable as a single textbook for a sequence of undergraduate courses on flight vehicle dynamics and control. Accompanied by a website that includes additional problems and a solutions manual. The book is essential reading for undergraduate students in mechanical and aerospace engineering, engineers working on flight vehicle control, and researchers from other

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engineering backgrounds working on related topics.

"Space Vehicle Dynamics and Control provides a solid foundation in dynamic modeling, analysis, and control of space vehicles. More than 200 figures, photographs, and tables are featured in detailed sections covering the fundamentals of controlling orbital, attitude, and structural motions of space vehicles. The textbook highlights a range of orbital maneuvering and control problems: orbital transfer, rendezvous, and halo orbit determination and control. Rotational maneuvering and attitude control problems of space vehicles under the influence of reaction jet firings, internal energy dissipation, or momentum transfer via reaction wheels and control moment gyros are treated in detail. The

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textbook also highlights the analysis and design of attitude control systems in the presence of structural flexibility and/or propellant sloshing. At the end of each chapter, Dr. Wie includes a helpful list of references for graduate students and working professionals studying spacecraft dynamics and control. A bibliography of more than 350 additional references in the field of spacecraft guidance, control, and dynamics is also provided at the end of the book. This text requires a thorough knowledge of vector and matrix algebra, calculus, ordinary differential equations, engineering mechanics, and linear system dynamics and control. The first two chapters provide a summary of such necessary background material. Since some problems may require the use of software for the analysis, control design, and numerical simulation, readers

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should have access to computational software (i.e., MATLAB) on a personal computer.

Spacecraft Dynamics and Control: The Embedded Model Control Approach provides a uniform and systematic way of approaching space engineering control problems from the standpoint of model-based control, using state-space equations as the key paradigm for simulation, design and implementation. The book introduces the Embedded Model Control methodology for the design and implementation of attitude and orbit control systems. The logic architecture is organized around the embedded model of the spacecraft and its surrounding environment. The model is compelled to include disturbance dynamics as a repository of the

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uncertainty that the control law must reject to meet attitude and orbit requirements within the uncertainty class. The source of the real-time uncertainty estimation/prediction is the model error signal, as it encodes the residual discrepancies between spacecraft measurements and model output. The embedded model and the uncertainty estimation feedback (noise estimator in the book) constitute the state predictor feeding the control law. Asymptotic pole placement (exploiting the asymptotes of closed-loop transfer functions) is the way to design and tune feedback loops around the embedded model (state predictor, control law, reference generator). The design versus the uncertainty class is driven by analytic stability and performance inequalities. The method is applied to several attitude and orbit control problems. The book begins with an

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extensive introduction to attitude geometry and algebra and ends with the core themes: state-space dynamics and Embedded Model Control. Fundamentals of orbit, attitude and environment dynamics are treated giving emphasis to state-space formulation, disturbance dynamics, state feedback and prediction, closed-loop stability. Sensors and actuators are treated giving emphasis to their dynamics and modelling of measurement errors. Numerical tables are included and their data employed for numerical simulations. Orbit and attitude control problems of the European GOCE mission are the inspiration of numerical exercises and simulations. The suite of the attitude control modes of a GOCE-like mission is designed and simulated around the so-called mission state predictor. Solved and unsolved exercises are included within

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the text - and not separated at the end of chapters - for better understanding, training and application. Simulated results and their graphical plots are developed through MATLAB/Simulink code.

Topics include orbital and attitude maneuvers, orbit establishment and orbit transfer, plane rotation, interplanetary transfer and hyperbolic passage, lunar transfer, reorientation with constant momentum, attitude determination, more. Answers to selected exercises. 1976 edition.

Get a complete understanding of aircraft control and simulation Aircraft Control and Simulation: Dynamics, Controls Design, and Autonomous Systems, Third Edition is a

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comprehensive guide to aircraft control and simulation. This updated text covers flight control systems, flight dynamics, aircraft modeling, and flight simulation from both classical design and modern perspectives, as well as two new chapters on the modeling, simulation, and adaptive control of unmanned aerial vehicles. With detailed examples, including relevant MATLAB calculations and FORTRAN codes, this approachable yet detailed reference also provides access to supplementary materials, including chapter problems and an instructor's solution manual. Aircraft control, as a subject area, combines an understanding of aerodynamics with knowledge of the physical systems of an aircraft. The ability to analyze the performance of an aircraft both in the real world and in computer-simulated flight is essential to

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maintaining proper control and function of the aircraft. Keeping up with the skills necessary to perform this analysis is critical for you to thrive in the aircraft control field. Explore a steadily progressing list of topics, including equations of motion and aerodynamics, classical controls, and more advanced control methods Consider detailed control design examples using computer numerical tools and simulation examples Understand control design methods as they are applied to aircraft nonlinear math models Access updated content about unmanned aircraft (UAVs) Aircraft Control and Simulation: Dynamics, Controls Design, and Autonomous Systems, Third Edition is an essential reference for engineers and designers involved in the development of aircraft and aerospace systems and computer-based flight simulations, as

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well as upper-level undergraduate and graduate students studying mechanical and aerospace engineering.

Compiled by leading authorities, Aerospace Navigation Systems is a compendium of chapters that present modern aircraft and spacecraft navigation methods based on up-to-date inertial, satellite, map matching and other guidance techniques. Ranging from the practical to the theoretical, this book covers navigational applications over a wide range of aerospace vehicles including aircraft, spacecraft and drones, both remotely controlled and operating as autonomous vehicles. It provides a comprehensive background of fundamental theory, the utilisation of newly-developed techniques, incorporates the most complex and advanced

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types of technical innovation currently available and presents a vision for future developments. Satellite Navigation Systems (SNS), long range navigation systems, short range navigation systems and navigational displays are introduced, and many other detailed topics include Radio Navigation Systems (RNS), Inertial Navigation Systems (INS), Homing Systems, Map Matching and other correlated-extremalsystems, and both optimal and sub-optimal filtering in integrated navigation systems.

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